

# GATEWAY 1-WIRE (DALLAS) through RS 485 Modbus RTU 1-WIRE-GWY-MOD







## Gateway 1-WIRE (DALLAS) for measuring temperatures, humidity, with i-button keys and communication RS 485 MODBUS RTU

- Connection up to 40 temperature sensors with measuring humidity,
   i-button keys through 2 buses with communication 1-WIRE (DALLAS). 1st bus
   = 20 temperatures + humidity or i-button keys.
- Easy and variable solution for measuring in object, in technology, remote measurement with bus.
- Unbeatable savings of financial costs for cables compared to other solutions:
   20 sensors on one bus (totally 40 sensors/1 unit).
- Easy installation into control cabinet.
- Interface RS 485, RS 232, USB
- Complete management through the application 1-WIRE-GWY Tool, baud rate and address settings, sensors addressing on positions, values displaying, firmware upgrade other necessary functions.
- Software support = library elements are ready (programs) for control systems of different producers.



and



#### **TECHNICAL DATA**

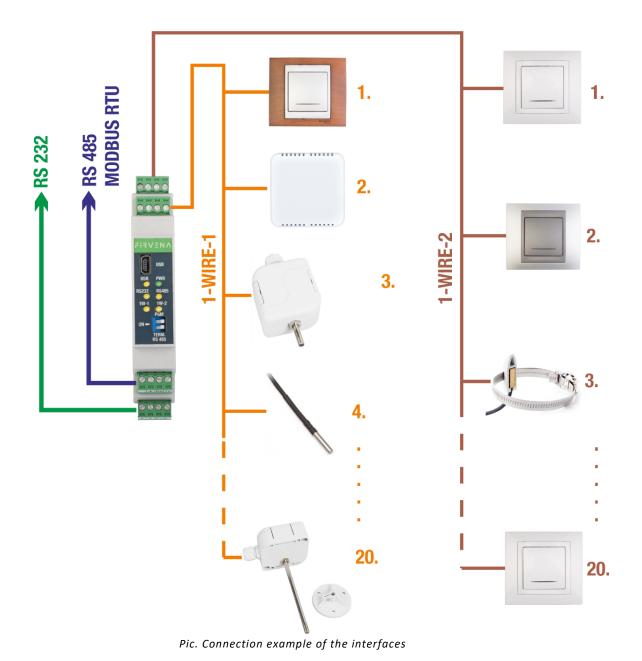
	rated voltage	24 V DC (recommended value for power supply)	
Electrical data	range possibility for power supply	10 – 25 V DC	
	own device consumption	80 mA (max.)	
	indication	yes, green LED diode on front panel of the device	
	type	RS 485 (TIA/EIA-485-A), RS-232	
	protocol	MODBUS RTU, slave, supported function 03, 06, 16	
Communication I.	baud rate for RS 485 and RS 232	optional (kBd) 1200, 1800, 2400, 4800, 7200, 9600, 14400, 19200, 28800, 38400, 56000, 57600, 76800, 115200, 128000, 230400	
	address	1-247	
	No. of devices on the bus RS 485	32	
	parita	no, even, odd	
	stopbit	1,2	
	galvanic isolation from power supply	yes	
	indication	yes, yellow LED diode on front panel of the device	
	type	1-WIRE (DALLAS)	
	protocol	1-WIRE (DALLAS)	
Communication	No. of temperature sensors on 1 bus	20	
II.	No. of buses (lines)	2	
	galvanic isolation from power supply	yes	
	indication of bus state	yes LED	
	cover	IP20	
Operating values	operating temperature	-20+70 °C	
	relative air humidity	max. 80 %	
	external dimension (h x w x d)	98 x 17,5 x 56,4mm	
	type	USB – pro service purposes	
	protocol	MODBUS RTU, slave, supported functions 03, 06, 16	
	baud rate	115 200 bps	
USB	address	1	
	parity	no	
	stopbit	1	
	indication	yes, yellow LED diode on front panel of the device	

#### **DESCRIPTION OF DEVICE FUNCTIONS**

Gateway 1-WIRE-GWY-MOD processes data from temperature sensors or i-button keys with communication 1-WIRE (DALLAS) on its two data buses. Each bus can serve up to 20 temperature sensors with information about humidity (totally 40) and send their values including faulty states through the interfaces RS 485, RS 232 with protocol MODBUS RTU. The gateway is configured through the application 1-WIRE-GWY-TOOL and USB cable for easy and simple management of sensors positions and all necessary settings. LED indicators on front panel indicate power of device, communication on RS 485, RS 232 and presence of temperature sensor for each bus separately.



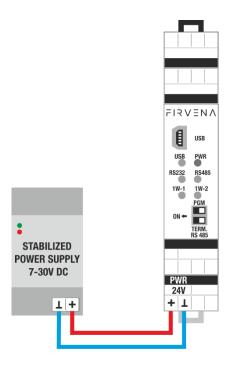
#### **EXAMPLE FOR CONNECTION OF THE INTERFACES**





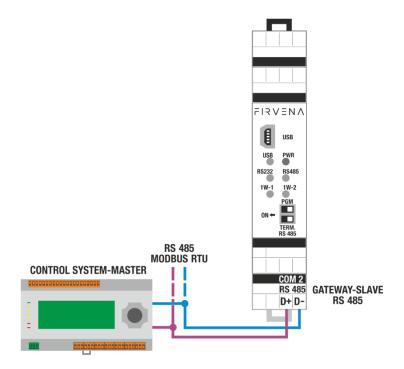
#### **CONNECTION OF POWER SUPPLY 24V, DC**

Power supply of the device is 8-27V (DC) with tolerance 10%.



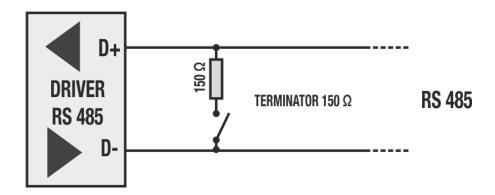
#### **CONNECTION OF COMMUNICATION RS 485**

Gateway can communicate through buses RS 485 and RS 232 at the same time.

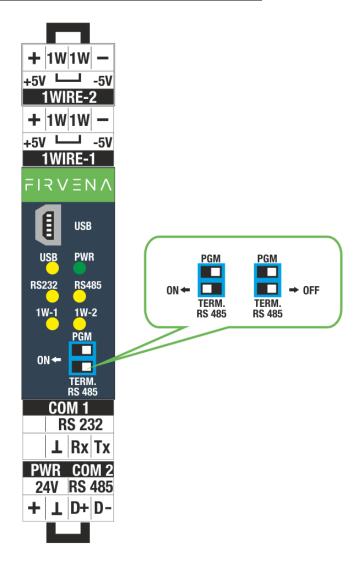




#### LOAD OF THE BUS RS 485 (TERMINATOR) BLOCK SCHEMA:



#### LOAD OF THE BUS RS 485 (TERMINATOR) SELECTION ON/OFF:



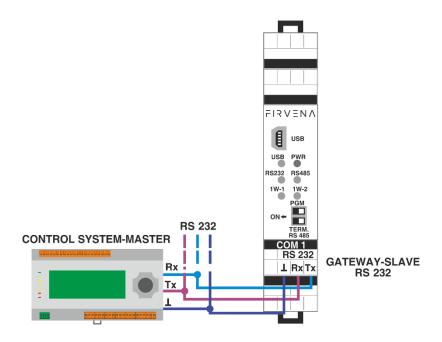


#### **BAUD RATE SETTINGS OF THE COMMUNICATION RS 485:**

Baud rate settings of communication and address for RS 485 is made in the application 1-WIRE-GWY Tool in [Gateway Settings > Port RS485]:



#### **CONNECTION OF COMMUNICATION RS 232**



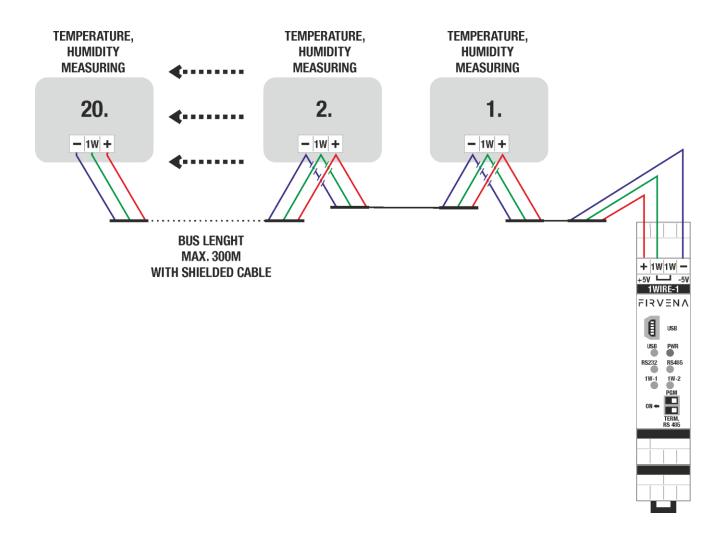
#### **BAUD RATE SETTINGS OF COMMUNICATION RS 232:**

Baud rate settings of communication and address for RS 232 is made in the application 1-WIRE-GWY Tool in [Gateway Settings > Port RS232]:



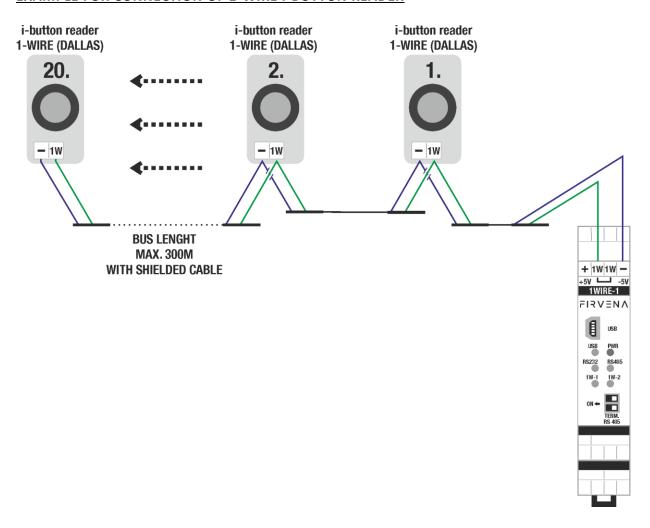
## FIRVENA

#### **EXAMPLE FOR CONNECTION OF SENSORS ON 1-WIRE**





#### **EXAMPLE FOR CONNECTION OF 1-WIRE I-BUTTON READER**



#### Notice for i-button keys:

Continuous communication runs between gateway and sensors on buses 1-WIRE-1 and 1-WIRE-2 in case of using 1-WIRE sensors. On the contrary in case of using i-button keys, the i-button reader is used as a reading medium and it waits for attaching an i-button key and after that the communication runs and gateway performes the instruction.

In case of connection of more i-button readers on one bus by the gateway and a user attaches i-button keys by more i-button readers at the same time, so the communication from the readers will overlap.

It is appropriate to think if such a situation may happen. The i-button readers can be divided in to both buses or the application can be extended with one another gateway.

#### Important notice:

It is not able to combine temperatures with i-button readers on one bus (1-WIRE-1 or 1-WIRE-2). The technical combination of temperature sensors and i-button keys is not possible! We recommend the division to the buses 1-WIRE-1 or 1-WIRE-2.

#### Reading the i-button key on position in gateway:

When reading the i-button key on position in gateway, the i-button key must be attached to the i-button reader. The i-button reader doesnt have identification!

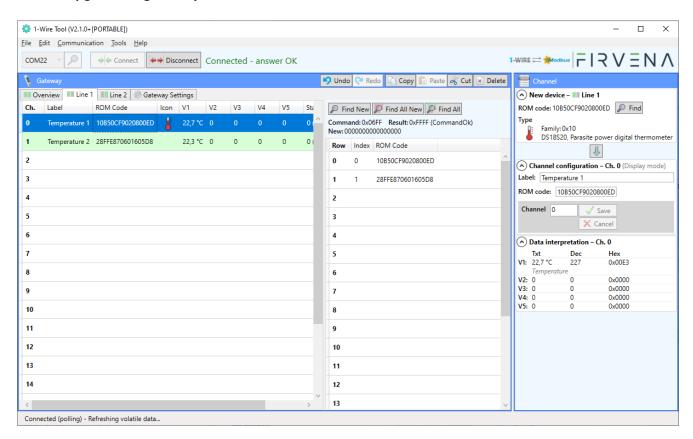


#### **CONFIGURATION AND GATEWAY SETTINGS**

Gateway settings, all necessary management is solved with the application 1-WIRE-GWY-Tool.

#### The application ensures:

- Communication through USB
- Configuration of baud rate and address for RS 232, RS 485
- Easy adding and removing on/from position of the 1-WIRE humidity sensor
- Easy adding and removing on/from position of the 1-WIRE i-button key
- The option to look up other unknown sensors and adding on position
- Comprehensive overview of all measured values, states, errors
- Upgrade of gateway's firmware



#### **UPGRADE OF FIRMWARE:**

It is described in a separate document.



### 1. Register MAP

O		No	Description
1		0	
2			
3   ROM code4 (serial number, CRC)			· · ·
4			· ·
1	e 1		
1	- Š		
7	۵		
R			
9 Error 10 ROM code1 (family code, serial number) 11 ROM code2 (serial number) 12 ROM code3 (serial number) 13 ROM code4 (serial number) 13 ROM code4 (serial number, CRC) 14 Value 1 (Temperature in °C) 15 Value 2 16 Value 3 17 Value 4 18 Value 5 19 Error 390 ROM code1 (family code, serial number) 391 ROM code2 (serial number) 392 ROM code3 (serial number) 393 ROM code4 (serial number, CRC) 395 Value 2 396 Value 3 397 Value 4 398 Value 5 399 Error  No Description 500 Device 1 – Error 501 Device 2 – Error 539 Device 40 – Value 1 541 Device 2 – Value 1 559 Device 40 – Value 2 581 Device 2 – Value 2 581 Device 2 – Value 3 660 Device 1 – Value 4 661 Device 2 – Value 4 665 Device 1 – Value 4 666 Device 1 – Value 4 667 Device 1 – Value 4 668 Device 1 – Value 4 669 Device 1 – Value 4			
10		-	
11   ROM code2 (serial number)   12   ROM code3 (serial number)   12   ROM code3 (serial number)   13   ROM code4 (serial number, CRC)   14   Value 1 (Temperature in "C)   15   Value 2   16   Value 3   17   Value 4   18   Value 5   19   Error			
12		-	
13			
14		-	, ,
16	e 2		
16	Š		
17	۵	-	
18			
19   Error			
1990   1990			
391   ROM code2 (serial number)   392   ROM code3 (serial number)   393   ROM code4 (serial number, CRC)   394   Value 1 (Temperature in °C)   395   Value 2   396   Value 3   397   Value 4   398   Value 5   399   Error			
391   ROM code2 (serial number)   392   ROM code3 (serial number)   393   ROM code4 (serial number, CRC)   394   Value 1 (Temperature in °C)   395   Value 2   396   Value 3   397   Value 4   398   Value 5   399   Error		390	ROM code1 (family code, serial number)
393   ROM code4 (serial number, CRC)   394   Value 1 (Temperature in °C)   395   Value 2   396   Value 3   397   Value 4   398   Value 5   399   Error		391	
393   ROM code4 (serial number, CRC)   394   Value 1 (Temperature in °C)   395   Value 2   396   Value 3   397   Value 4   398   Value 5   399   Error		392	ROM code3 (serial number)
394   Value 1 (Temperature in °C)   395   Value 2   396   Value 3   397   Value 4   398   Value 5   399   Error	0		
396   Value 3   397   Value 4   398   Value 5   399   Error	e 4		
396   Value 3   397   Value 4   398   Value 5   399   Error	.×ic	395	· · ·
398    Value 5   399    Error	۵	396	Value 3
399   Error   No   Description		397	Value 4
399   Error   No   Description			
Solidar   Device 1 - Error   Solidar   Device 2 - Error   Solidar   Solida		399	Error
Soli   Device 2 - Error   Soli   Device 40 - Error   Soli   Device 40 - Error   Soli   Device 1 - Value 1   Soli   Device 2 - Value 1   Soli   Device 40 - Value 1   Soli   Device 40 - Value 2   Soli   Device 2 - Value 2   Soli   Device 40 - Value 2   Soli   Device 40 - Value 2   Soli   Device 40 - Value 3   Soli   Device 40 - Value 4   Soli   Device 40 - Value		No	Description
Soli   Device 2 - Error   Soli   Device 40 - Error   Soli   Device 40 - Error   Soli   Device 1 - Value 1   Soli   Device 2 - Value 1   Soli   Device 40 - Value 1   Soli   Device 40 - Value 2   Soli   Device 2 - Value 2   Soli   Device 40 - Value 2   Soli   Device 40 - Value 2   Soli   Device 40 - Value 3   Soli   Device 40 - Value 4   Soli   Device 40 - Value		500	Device 1 – Error
S39   Device 40 - Error   S40   Device 1 - Value 1   S41   Device 2 - Value 1   S79   Device 40 - Value 1   S80   Device 1 - Value 2   S81   Device 2 - Value 2   S81   Device 40 - Value 2   S81   Device 40 - Value 2   S81   Device 40 - Value 3   S621   Device 2 - Value 3   S621   Device 2 - Value 3   S621   Device 40 - Value 3   S621   Device 40 - Value 3   S631   Device 40 - Value 3   S642   Device 40 - Value 4   S653   Device 40 - Value 4   S664   Device 2 - Value 4   S665   Device 2 - Value 4   S6666   Device 2 - Value 4   S667   Device 3 - Value 4   S667   Device 40 - Value 4   S667   Device 2 - Value 4   S667   Device 40 - Value 4   S667   Dev	or	501	
S40   Device 1 - Value 1   S41   Device 2 - Value 1   S79   Device 40 - Value 1   S80   Device 1 - Value 2   S81   Device 2 - Value 2   S81   Device 2 - Value 2   S81   Device 40 - Value 2   S81   Device 40 - Value 2   S81   Device 2 - Value 3   S80   Device 1 - Value 3   S80   Device 2 - Value 3   S80   Device 40 - Value 3   S80   Device 40 - Value 4   Device 40 - Valu	Err		
S41   Device 2 - Value 1		539	Device 40 –Error
S79   Device 40 - Value 1	_	540	Device 1 –Value 1
S79   Device 40 - Value 1	le 1	541	Device 2 –Value 1
S79   Device 40 - Value 1	/alu		
S81   Device 2 - Value 2	_	579	Device 40 – Value 1
619 Device 40 – Value 2  620 Device 1 – Value 3  621 Device 2 – Value 3   659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4	۵.	580	Device 1 – Value 2
619 Device 40 – Value 2  620 Device 1 – Value 3  621 Device 2 – Value 3   659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4	Je 2	581	Device 2 – Value 2
619 Device 40 – Value 2  620 Device 1 – Value 3  621 Device 2 – Value 3   659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4	/alı		
621 Device 2 – Value 3 659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4		•••	
659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4			Device 40 – Value 2
659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4	~	619	
659 Device 40 – Value 3  660 Device 1 – Value 4  661 Device 2 – Value 4	s er	619 620	Device 1 – Value 3
661 Device 2 –Value 4	/alue 3	619 620 621	Device 1 – Value 3
661 Device 2 –Value 4	Value 3	619 620 621	Device 1 – Value 3 Device 2 – Value 3
		619 620 621  659	Device 1 – Value 3  Device 2 – Value 3  Device 40 – Value 3
i e i i i i i i i i i i i i i i i i i i		619 620 621  659 660	Device 1 – Value 3 Device 2 – Value 3 Device 40 – Value 3 Device 1 – Value 4
699 Device 40 – Value 4		619 620 621  659 660 661	Device 1 – Value 3 Device 2 – Value 3  Device 40 – Value 3  Device 1 – Value 4  Device 2 – Value 4



	700	Device 1 – Value 5			
Value 5	701	Device 2 – Value 5			
ηne		Device 2 Value 3			
>	739	Device 40 – Value 5			
	No	Description			
	1000	SW Version			
	1001	MODBUS address			
	1001	Baud rate (1200,115200)	PORT RS485		
	1002	MODBUS address			
	1003	Baud rate (1200,115200)	PORT RS232		
	1005	Stopbit 1, 2			
	1006	Parity 0- none, 1 - ODD, 2-EVEN	PORT RS485		
	1007	Stopbit 1, 2			
	1008	PORTR'			
ers	1009	HW Version			
iste	1010	Command			
Service registers	1011	Status			
ice	1012	NEW ROM code1 (family code, serial number)			
ē	1013	TINE 1			
S	1014	NEW ROM code3 (serial number)			
	1015	NEW ROM code4 (serial number, CRC)			
		, , ,			
	1020	Command			
	1021	Status			
	1022	NEW ROM code1 (family code, serial number)	LINES		
	1023	NEW ROM code2 (serial number)	LINE2		
	1024	NEW ROM code3 (serial number)			
	1025	NEW ROM code4 (serial number, CRC)			
	1053	Time delay 0 – 200ms PORT RS485			
	1054	Time delay 0 – 200ms PORT RS232			
	1055	Power 1Wire lines (0-OFF, 1- ON, 2,3, 5) (default 1-ON)			

	No	Description	
	1100	ROM code1 (family code, serial number)	
	1101	ROM code2 (serial number)	
	1102	ROM code3 (serial number)	
	1103	ROM code4 (serial number, CRC)	
	1104	Index 0	
	1105	ROM code1 (family code, serial number)	
	1106	ROM code2 (serial number)	
LIS	1107	ROM code3 (serial number)	LINF 1
iste	1108	ROM code4 (serial number, CRC)	LINE 1
Service registers	1109	Index 1	
l e			
ΪŽ	1195	ROM code1 (family code, serial number)	
SS	1196	ROM code2 (serial number)	
	1197	ROM code3 (serial number)	
	1198	ROM code4 (serial number, CRC)	
	1199	Index 19	
	1200	ROM code1 (family code, serial number)	
	1201	ROM code2 (serial number)	LINE 2
	1202	ROM code3 (serial number)	



1203	ROM code4 (serial number, CRC)	
1204	Index 0	
1205	ROM code1 (family code, serial number)	
1206	ROM code2 (serial number)	
1207	ROM code3 (serial number)	
1208	ROM code4 (serial number, CRC)	
1209	Index 1	
1295	ROM code1 (family code, serial number)	
1296	ROM code2 (serial number)	
1297	ROM code3 (serial number)	
1298	ROM code4 (serial number, CRC)	
1299	Index 19	
5000	Device 1 - Error counter (crc, timeout) 0-65000 (write 0)	
5001	Device 2 - Error counter (crc, timeout) 0-65000	LINE 1
		LIINE I
5019	Device 20 - Error counter (crc, timeout) 0-65000	
5020	Device 21 - Error counter (crc, timeout) 0-65000	
5021	Device 22 - Error counter (crc, timeout) 0-65000	LINE 2
		LIINE Z
5039	Device 40 - Error counter (crc, timeout) 0-65000	

### 2. Description of registers

It is assigned 10 registers to each sensor. 4 registers with editable serial number, 5 with read data and 1 error.

#### Registers with serial number

Register No.	Higher byte	Lower byte	Note
n*10 + 0	8bit family code	serial number - 1	
n*10 + 1	serial number - 2	serial number - 3	
n*10 + 2	serial number - 4	serial number - 5	
n*10 + 3	serial number 6	serial number - 7	
n*10 + 4	serial number - 8	CRC	

<sup>\*</sup>n is number of channel (input)

#### **Data registers**

Register No.	Value	Note
n*10 + 5	Temperature * 10	23,5°C -> 235
n*10 + 6	For DS2438 voltage napětí or 0	UNICA module humidity - voltage
n*10 + 7	For DS2438 current or 0	UNICA module lighting ratio 0-1023( 0-100%)
n*10 + 8	Approximate relative humidity	Approximate relative humidity %
n*10 + 9	Status / Configuration	Page 0 MemMap DS2438

<sup>\*</sup>n is number of channel (input)

#### iButtons

Register No.	Value	Note
n*10 + 5	1 Presence of i-button key	0,1
n*10 + 6	No. of i-button key connection	0 - 65353
n*10 + 7	0	



n*10 + 8	0	
n*10 + 9	1	It holds state 20s after disconnection of i-
		button key

<sup>\*</sup>n is number of channel (input)

#### **Error register**

Register No.	Value	Note
n*10 + 9	1 - 255	State of communication with sensor

<sup>\*</sup>n je číslo kanálu (vstupu)

Error register	
Value	Meaning of value
0	Bus Ok
1	No sensor on bus (bus is interrupted)
2	Bus short-circuit
3	Type of sensor is not supported
4	Error CRC
5	Error in reply – the sensor is not connected
255	Not occupied position

If the sensor shows an error, all its values are set -2800 (nonsensical value).

The data fields from registers 0...399 are grouped by their type in registers 500...739. This allows reading actual data without ROM code and unused values using less number of Modbus requests.

#### 3. Description of service registers

Registers COMMAND and STATUS are available for each bus for editing field of registers.

Register "Command". It is possible to modify register table with this row. row. First byte contains command, second one number of channel. Channels are number from zero.

Register No.		Dogistor description
Bus 1	Bus 2	Register description
1010	1020	Command

#### Example:

Command	Command – meaning of values					
Value in	Command	Command	Description of command			
register	HiByte	LoByte				
0x0F02	0x0F	0x02	Delete sensor on position 2			
0x05FF	0x05	FF= no	Search new ROM Code			
			Command is usable when one device only in on			
			the bus			
0x06FF	0x06	FF=no	Search ROM Code of all uknown devices that are			
			connected to bus			
0x07FF	0x07	FF=no	Search ROM Code of all devices that are			
			connected to bus. Also the saved ones.			
0x8208	0x82	0x08	Newly found ROM Code with index 2 will be			
			saved on position 8*			
0x0902	0x09	0x02	Save new ROM Code on position 2			

<sup>\*</sup>Attention, on second bus the position 20 on position 20 is 0x9414



Register "Status". This register contains respond on "Command".

Register No.		Register description			
Bus 1	Bus 2	register description			
1011	1021	Status			

- After finishing the command, the number 0xFFFF runs
- If an error occurs during command, number of error (0xEEE0...A) returns to register status.

Status – meaning of values				
0xFFFF	Command ran without error			
0xEEE1	Number of channel is out of range for appropriate bus			
0xEEE2	Number of command is not supported			
0xEEE3	Error during reading ROM-CODE			
0xEEE4	Error Chyba CRC during reading ROM-CODE			

Register "**NEW ROM code".** It will be written read ROM code into such marked registers. After command 0x5FF. Only one set of registers is for each bus.

Register No.		Register description		
Bus 1	Bus 2	Higher byte	Lower byte	
1012	1022	8bit family code	serial number - 1	
1013	1023	serial number - 2	serial number - 3	
1014	1024	serial number - 4	serial number - 5	
1015	1025	serial number - 6	serial number - 7	
1016	1026	serial number - 8	CRC	

Registr "Statistics". It will be written read ROM code into such marked registers. After command 0x5FF. Only one set of registers is for each bus.

Register No.		0.	Register description
PORT1	PORT2	PORT2	
1030	1040	1050	Number of received messages
1031	1041	1051	Number of sent messages
1032	1042	1052	Number of error messages

Register No.	Description
7.00	Setting of time – delay
1053 (1054)	Gateway waits for some time with sending respond after receiving message from master. This time consists of basic time (for baud rate 9600 it is 4 ms) and set value time delay. Some devices need longer time for switching from sending to receiving. When time is longered before sending respond, it can solve this problem.
	Both buses have the same power supply. This power supply is with DC-DC separated from communication ports, USB and main power supply. If there is problem with sensors on the bus, one of the option to run communication agagin may be short-term disconnection from power supply.
1055	Disconnection from power supply is controlled with register 1055.
	Following options are offered:
	0 – Disconnection from power supply
	1 – Connected to power supply (Default)



2 – Connected to power supply. If a sensor shows 3x in a row timeout or error, it will happen disconnection from power supply for approximately 5 s and then connection.

Another disconnection for 5 s and connection can be in one minute.

- 3 The same as point 2. Difference is that another disconnection for 5 s and connection can be in 5 minutes (default 3).
- 4 The same as point 2. Difference is that another disconnection for 5 s can be in 10 minutes.
- 5 The same as point 2. Difference is that another disconnection for 5 x can be in 15 minutes.

If i-button is used on a bus, set the register 1055 on value 1!!!

Registers for newly found sensors. When using commands for searching new sensors the results are saved into following table.

	No	Description			
	1100	ROM code1 (family code, serial number)			
	1101	ROM code2 (serial number)			
	1102	ROM code3 (serial number)			
	1103	ROM code4 (serial number, CRC)			
	1104	Index 0			
	1105	ROM code1 (family code, serial number)			
	1106	ROM code2 (serial number)			
	1107	ROM code3 (serial number)	LINE 1		
	1108	ROM code4 (serial number, CRC)	LIINE I		
	1109	Index 1			
	1195	ROM code1 (family code, serial number)			
	1196	ROM code2 (serial number)			
(0	1197	ROM code3 (serial number)			
ters	1198	ROM code4 (serial number, CRC)			
. <u>g</u>	1199	Index 19			
Service registers					
vic.	1200	ROM code1 (family code, serial number)			
Ser	1201	ROM code2 (serial number)			
	1202	ROM code3 (serial number)			
	1203	ROM code4 (serial number, CRC)			
	1204	Index 0			
	1205	ROM code1 (family code, serial number)			
	1206	ROM code2 (serial number)			
	1207	ROM code3 (serial number)			
	1208	ROM code4 (serial number, CRC)			
	1209	Index 1			
	1295	ROM code1 (family code, serial number)			
	1296	ROM code2 (serial number)			
	1297	ROM code3 (serial number)			
	1298	ROM code4 (serial number, CRC)			
	1299	Index 19			



#### Adding a new device (sensor)

You can add new sensor in two ways:

#### 1. Empty bus

- New sensor is connected to empty bus.
- ROM code of this sensor is read by writing value 0x05FF into the register 1010 for the bus 1 or 1020 for the bus 2. (numbering from zero)
- Read number is saved by writing value 0x09nn into the register 1010 (or 1020). The position is determined by number nn in hex.

#### 2. Occupied bus

- New sensor is connected to the bus with connected sensors.
- By writing value into the register 1010 (or 1020), all new ROM codes of sensors (max. 20) that are not saved yet, occur
- New codes occur in registers 1100 1199. 5 registers are assigned for each new sensor. Always the 5th register displays the position.
- New found sensor is written on appropriate position by writing value (e.g. 0x8208). Value consists of as follows. Higher byte displays position + 128 (in 1100-1199) from which ROM code is selected. Lower byte is position on which it is saved.
- Example: 1100 1104 is zero position (0x80), 1105 1109 is first position (0x81).. etc.
- If I want to save first position on position 12, the value written into register the 1010 will look like as follows: 0x810C.
- Indicator LED indicating state on bus flickers during searching.

No	Description		COMMAND	No	Description		
1100	ROM code1 0x28B0			0	ROM code1 <b>0x10DA</b>		
1101	ROM code2 0x0E59	0		1	ROM code2 0xF8F7		
1102	ROM code3 <b>0x0700</b>	Index 0		2	ROM code3 0x0208		
1103	ROM code4 0x008A	<u>ء</u>		3	ROM code4 0x00A6	] _	
1104	Index 0			4	Value 1	0 xe	
1105	ROM code1 0x1094			5	Value 2	Index	
1106	ROM code2 0xA516	$\forall$		6	Value 3	_	
1107	ROM code3 0x0308	dex		7	Value 4		
1108	ROM code4 0x00D4	ī	$\sim$	8	Value 5		
1109	Index 1			9	Error		
1110	ROM code1			10	ROM code1 0x1094		
1111	ROM code2	7	0,000	11	ROM code2 0xA516		
1112	ROM code3	Index	0x80 + 0x01	12	ROM code3 0x0308		
1113	ROM code4	<u>ء</u>		13	ROM code4 0x00D4		
1114	Index 2		000101	14	Value 1	1	
1115	ROM code1		0X8101	15	Value 2	Index	
1116	ROM code2			16	Value 3	Inc	
1117	ROM code3	m ×		17	Value 4		
1118	ROM code4	Index	) 	18	Value 5		
1119	Index 3	=	<u>≤</u> 0x01		Error		

Found serial numbers on bus 1 cannot be written on bus 2 and on the contrary.



Bus 1				Bus 2			
Position	Position	Result value	Result value	Position	Position	Result value	Result value
from	where	in hex.	in dec.	from	where	in hex.	in dec.
0	0	8000	32768	20	20	9414	37908
1	1	8101	33025	21	21	9515	38165
2	2	8202	33282	22	22	9616	38422
3	3	8303	33539	23	23	9717	38679
4	4	8404	33796	24	24	9818	38936
5	5	8505	34053	25	25	9919	39193
6	6	8606	34310	26	26	9A1A	39450
7	7	8707	34567	27	27	9B1B	39707
8	8	8808	34824	28	28	9C1C	39964
9	9	8909	35081	29	29	9D1D	40221
10	10	8A0A	35338	30	30	9E1E	40478
11	11	8B0B	35595	31	31	9F1F	40735
12	12	8C0C	35852	32	32	A020	40992
13	13	8D0D	36109	33	33	A121	41249
14	14	8E0E	36366	34	34	A222	41506
15	15	8F0F	36623	35	35	A323	41763
16	16	9010	36880	36	36	A424	42020
17	17	9111	37137	37	37	A525	42277
18	18	9212	37394	38	38	A626	42534
19	19	9313	37651	39	39	A727	42791

#### Example:

New ROM code is displayed in registers 1200-1203. It is such a data in the register 1204 that shows us it is 20th position.

So we will write COM code from the position 20 on position 33.

For calculation it is possible to use following formula:

Result value = (Position from + 128) \* 256 + Position where

Result value = (20+128)\*256+33 Result value = 37921 = 9421 Hex



## **Revision history**

Tab. Document revision history

Date	Version	Modifications made
10th October 2018	1.7	Repair connection RS 232, text corrections
17th December 2018	1.8	Repair of technical information
14th September 2023	1.9	Text corrections
23rd October 2023	1.10	Updated to firmware V2.02. Added description of registers 500739. Updated 1-WIRE-GWY Tool screenshots.